



NASA STTR 2015 Phase I Solicitation

T4 Robotics, Tele-Robotics and Autonomous Systems

Lead Center: HQ

The topic for Robotics, Tele-Robotics and Autonomous Systems, consists of seven technology subareas: Sensing and Perception; Mobility; Manipulation; Human-Systems Integration; Autonomy; Autonomous Rendezvous and Docking (AR&D); and Robotics, Tele-Robotics and Autonomous Systems Engineering. Robotics, Tele-Robotics and Autonomous Systems supports NASA space missions with the development of new capabilities, and can extend the reach of human and robotic exploration through a combination of dexterous robotics, better human/robotic interfaces, improved mobility systems, and greater sensing and perception. The Robotics, Tele-Robotics and Autonomous Systems topics focuses on several key issues for the future of robotics and autonomy: enhancing or exceeding human performance in sensing, piloting, driving, manipulating, and rendezvous and docking; development of cooperative and safe human interfaces to form human-robot teams; and improvements in autonomy to make human crews independent from Earth and make robotic missions more capable.

Subtopics

T4.01 Dynamic Servoelastic (DSE) Network Control, Modeling and Optimization

Lead Center: AFRC

Participating Center(s): ARC, JPL, LaRC

This subtopic addresses advanced control-oriented techniques for dynamic servoelastic (DSE) terrestrial, planetary, and space environment flight systems using distributed network sensor and control systems. Methods include modeling, simulation, optimization and stabilization of DSE systems to actively and/or adaptively control structural dynamic geometry/topology, vibration, atmospheric and intraspace disturbances, static/dynamic loads, and other structural dynamic objectives for enhanced dynamic servoelastic performance and stability characteristics.

- DSE control for performance enhancements while minimizing dynamic interaction.
- Flexible aircraft and spacecraft stabilization and performance optimization.
- Modeling and system identification of distributed DSE dynamics.
- Sensor/actuator developments and modeling for distributed DSE control.
- Uncertainty modeling of complex DSE system behavior and interactions.
- Distributed networked sensing and control for vehicle shape, vibration, and load control.

This subtopic also addresses capabilities enabling design solutions for performance and environmental challenges of future air and space vehicles. Research in revolutionary aerospace configurations include lighter and more

flexible materials, improved propulsion systems, and advanced concepts for high lift/performance and drag/energy reduction. This subtopic targets efficiency and environmental compatibilities requiring performance challenges and novel control-oriented techniques for aero-servoelastic considerations which are gaining prevalence in advanced aerospace flight vehicles, atmospheric and extra-terrestrial.

Technical elements for the Phase I proposals may also include:

- Mission/maneuver adaptivity with dissipative optimal energy-force distribution.
- Data-driven multi-objective DSE control with physics-based sensing.
- Robust sensing-control-communication networks for sensor-based distributed control.
- Compressive information-based sensing and information structures.
- Evolving systems as applied to self-assembling and robotic maneuvering.
- Scalable and evolvable information networks with layering architectures.
- Modular architectures for distributed autonomous aerospace systems.
- Multi-objective, multi-level control and estimation architectures.
- Distributed multi-vehicle dynamics analysis and visualization with complex simulations.
- Reduced order modeling capable of substructure coupling of nonlinear materials.

Development of distributed sensory-driven control-oriented DSE systems is solicited to enable future flight vehicle concepts and designs that manage structural dynamic uncertainty on a vehicle's overall performance. Proposals should assist in revolutionizing improvements in performance to empower a new generation of air and space vehicles to meet the challenges of terrestrial and commercial space concerns with novel concepts and technology developments in systems analysis, integration and evaluation. Higher performance measures include energy efficiency to reduce fuel burn and operability technologies that enable information network decompositions that have different characteristics in efficiency, robustness, and asymmetry of information and control with tradeoff between computation and communication.

Advanced mission applicability in Phase II should show the ability of aerospace GN&C systems to achieve mission objectives as a function of GN&C sensor performance, vehicle actuation/power/energy, and the ability to jointly design them as onboard-capable, real-time computing platforms with applicable environmental effects and robust guidance algorithms.

State of the Art

This subtopic will:

- Provide capabilities that would enable new projects and missions that are not currently feasible, using distributed sensing and controls for network processing.
- Impact multiple missions in NASA space operations and science, earth science, and aeronautics.
- Be influential across aerospace and non-aerospace disciplines with dynamic interactions.

Potential technical impacts are:

- Vehicle energy efficiency with passive/active dissipativity for control and dynamic stability with extreme power constraints.
- Weight minimization through dynamic servoelastic control.
- Mission adaptivity and robustness with real-time, consensus-coordinated control dealing with computation, communication, and dynamics.

New technologies proposed should have the potential to impact the following NASA missions:

- Data availability for science missions.
- Mission planning.
- Autonomous rendezvous/docking technology.
- Environmental monitoring for human habitation.

Apart from NASA missions, the aeronautics technology could be adapted for development and use in autonomous operation of wind/ocean energy and smart space power grid systems in dynamic environments. There are number of advantages to exploring this subtopic technology:

- Increase in autonomy and fuel efficiency of coordinated robotic vehicles and sub-components.
- Improved science, atmospheric, and reconnaissance data.
- Cost, risk and reliability of flight vehicles for a terrestrial, planetary, or space mission.
- Inter-networks with improved dynamic behavior.

Potential technical impacts are:

- Vehicle energy efficiency with passive/active dissipativity for control and dynamic stability with extreme power constraints.
- Weight minimization through dynamic servoelectric control.
- Mission adaptivity and robustness with real-time, consensus-coordinated control dealing with computation, communication, and dynamics.

T4.02 Regolith Resource Robotic

Lead Center: KSC

Participating Center(s): ARC, LaRC

Using resources in space is the first step towards human self-sufficiency while expanding its presence into the Solar System. The use of robotics for In-Situ Resource Utilization (ISRU) in outer space on various planetary bodies is essential since ISRU requires large quantities of local regolith that must be acquired and processed by capable machines. In some cases this will happen prior to crew arrival on site, or it will take place at a remote destination where the crew cannot spend much time due to radiation exposure limits or other constraints. In addition, communications latencies at remote locations such as Asteroids mandate autonomous robotics applications.

The first step towards using resources derived from small bodies in space, Mars, Mars Moons and Earth's Moon, such as water, volatiles, metals and organic compounds, is to visit a target body, prospect it with sample acquisition devices and subsequently do characterization of these samples. This data will feed into eventual missions and methods for using resources in outer space by mining the ore on these target bodies and then transforming it into useful products via In-Situ Resource Utilization (ISRU) and advanced manufacturing techniques such as Additive Manufacturing and Construction. For these reasons, resource prospecting, identification and sampling regolith for characterization are priorities in this sub-topic.

Proposals are sought for innovative resource prospecting mission concepts, technology development, and demonstrations.

Technologies include sample acquisition methods and devices, regolith anchoring methods, autonomous conops, sub-surface access, excavation, specialized sensors, dust lofting mitigation, perception in dusty environments, mobility methods, surveying, remote sample characterization, geodetic mapping, replenishing and transferring robotic commodities such as propellants, electric power, data transfer, pneumatics and robust interfaces for commodity transfer.

Future prospecting missions include:

- Water/Ice on Mars, Mars moons or Earth's Moon.
- Micro-gravity Near Earth Object (NEO) operations to prospect/sample surface resources.
- Lava tubes/shadowed crater cold traps on planetary surfaces to characterize volatiles accumulation.

