Range Safety requires accurate and reliable tracking data for launch vehicles. Onboard GPS receivers must maintain lock, reacquire very quickly and operate securely in a highly-dynamic environment. GPS Course Acquisition Code (CA) does not require classified decryption codes and has an accuracy of better than 30 m and 1 m/s. Although this accuracy is good enough for most Range Safety needs, better accuracy is needed for antenna pointing, docking maneuvers and attitude determination. CA code also offers little protection against deliberately transmitted false signals or "spoofing".

This solicitation seeks proposals in the following areas:

- **Innovative technologies to increase the accuracy of the L1 C/A navigation solution by combining the pseudo ranges and phases of the L1 C/A signals, and use of the L2 and L5 carrier.** Factors that degrade the GPS signal can be obtained by differencing the available carrier phase and pseudo range measurements and then removing this difference from the navigation solution.

- **Technologies that combine spatial processing of signals from multiple antennas with temporal processing techniques to mitigate interference signals received by the GPS receiver.** The coordinated response of adaptive pattern control (beam and null steering) and digital excision of certain interfering signal components minimizes strong jamming signals. Adaptive nulling minimizes interfering signals by the optimal control of the GPS antenna pattern (null steering).

These technologies should be independent of any particular GPS receiver design.

Research should be conducted to demonstrate technical feasibility during Phase 1 and show a path toward a Phase 2 hardware and software demonstration unit or software package for NASA testing at the completion of the Phase 2 contract.