NASA SBIR 2009 Phase I Solicitation

A1.09 Pilot Interactions with Adaptive Control Systems under Off-Nominal Conditions

Lead Center: ARC

Participating Center(s): AFRC

Adaptive control is a promising control technology that can enhance flight safety and performance. Adaptive control has been demonstrated to provide improved performance in many unmanned aerial systems. When operated in an autonomous mode such as in an autopilot, the behavior of an adaptive flight control system can be modeled and simulated with a sufficient degree of repeatability.

The presence of a pilot working in a closed-loop fashion with an adaptive flight control presents an important problem that has not been well addressed. Adaptive control generally requires sufficiently rich input signals to improve parameter convergence, as the adaptive control system adapts to parametric changes in the vehicle dynamics or exogenous disturbances. The condition for rich input signals is known as persistent excitation. During adaptation under off-nominal conditions such as aircraft with damage, the pilot provides persistently exciting signals to the adaptive control system. There is generally a trade-off between adaptation and stability due to persistent excitation. With a high persistent excitation in the pilot inputs, the speed of adaptation increases and in theory better handling performance could be achieved. However, in practice, the high persistent excitation in the control signals can potentially cause significant cross-coupling between different flight control axes and or excite unmodeled dynamics such as aeroservoelastic modes. The overall effect of high persistent excitation could aggravate stability robustness of an adaptive flight control system with a pilot in the loop that results in poor handling qualities.

Another aspect of pilot interactions with an adaptive control system is the potential interactions between two adaptive elements in a closed-loop fashion, because the pilot can also be viewed as an adaptive control system with a learning ability. With the pilot adaptive element providing high persistently exciting inputs into an adaptive flight control system with a predetermined adaptation rate, the issue of stability can be important and difficult to assess.

To enable an adaptive flight control system to be operated with a pilot in the loop, it is necessary to develop new research techniques that can assess the effects of pilot interactions with an adaptive flight control system. These techniques should address pilot control responses via an adaptive model with features that can capture relevant interactions with an adaptive flight control system. Techniques for assessing pilot interactions via metrics that can quantify the pilot-vehicle system responses with an adaptive flight control system are also needed. Other aspects of the research can include new methods and tools that can provide an advisory function to limit the pilot control inputs in order to trade off between command-following performance and stability robustness.

Research in adaptive control methods will address the system requirements to provide good flying characteristics when the human operator closes the control loop. In the presence of damage, failures, etc. the adaptive system must trade the stability requirements with closed loop handling requirements. Methods for selecting the best achievable handling are needed. The adaptation system needs to find a good compromise between suppression of coupling between the axis (i.e. pitch into roll, etc.) and good in-axis behavior. Better metrics to assess cross-coupled (asymmetric) behavior are needed. These metrics could provide a quantitative measurement of the severity of a given failure, as well as a measure of the improvement due to adaptation. As the adaptation changes the flying characteristics of the vehicle, some means of informing the operator is required to ensure that the system is not overdriven by a pilot who is expecting nominal performance.